

ebm-papst Mulfingen GmbH & Co. KG

Bachmühle 2 · D-74673 Mulfingen

Phone +49 7938 81-0

Fax +49 7938 81-110

info1@de.ebmpapst.com

www.ebmpapst.com

Limited partnership · Headquarters Mulfingen

County court Stuttgart · HRA 590344

General partner: Elektrobau Mulfingen GmbH · Headquarters Mulfingen

County court Stuttgart · HRB 590142

**Nominal data**

Type	S3G500-AM56-24		
Motor	M3G112-EA		
Phase		1~	1~
Nominal voltage	VAC	230	230
Nominal voltage range	VAC	200 .. 277	200 .. 277
Frequency	Hz	50/60	50/60
Type of data definition		ml	ml
State			prelim.
Speed	min ⁻¹	1420	1420
Power input	W	750	750
Current draw	A	3.4	3.4
Max. back pressure	Pa	175	175
Min. ambient temperature	°C	-25	-25
Max. ambient temperature	°C	+60	+60

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive integrated	Integrated
Specific ratio*	1,00

* Specific ratio = $1 + p_b / 100\,000\text{ Pa}$

	Actual	Request 2013	Request 2015
Overall efficiency η_{es}	41,6	28,8	32,8
Efficiency grade N	48,8	36	40
Power input P_{ed}	kW	0,73	
Air flow q_v	m ³ /h	5850	
Pressure increase p_{fs}	Pa	173	
Speed n	min ⁻¹	1425	

Data established at point of optimum efficiency

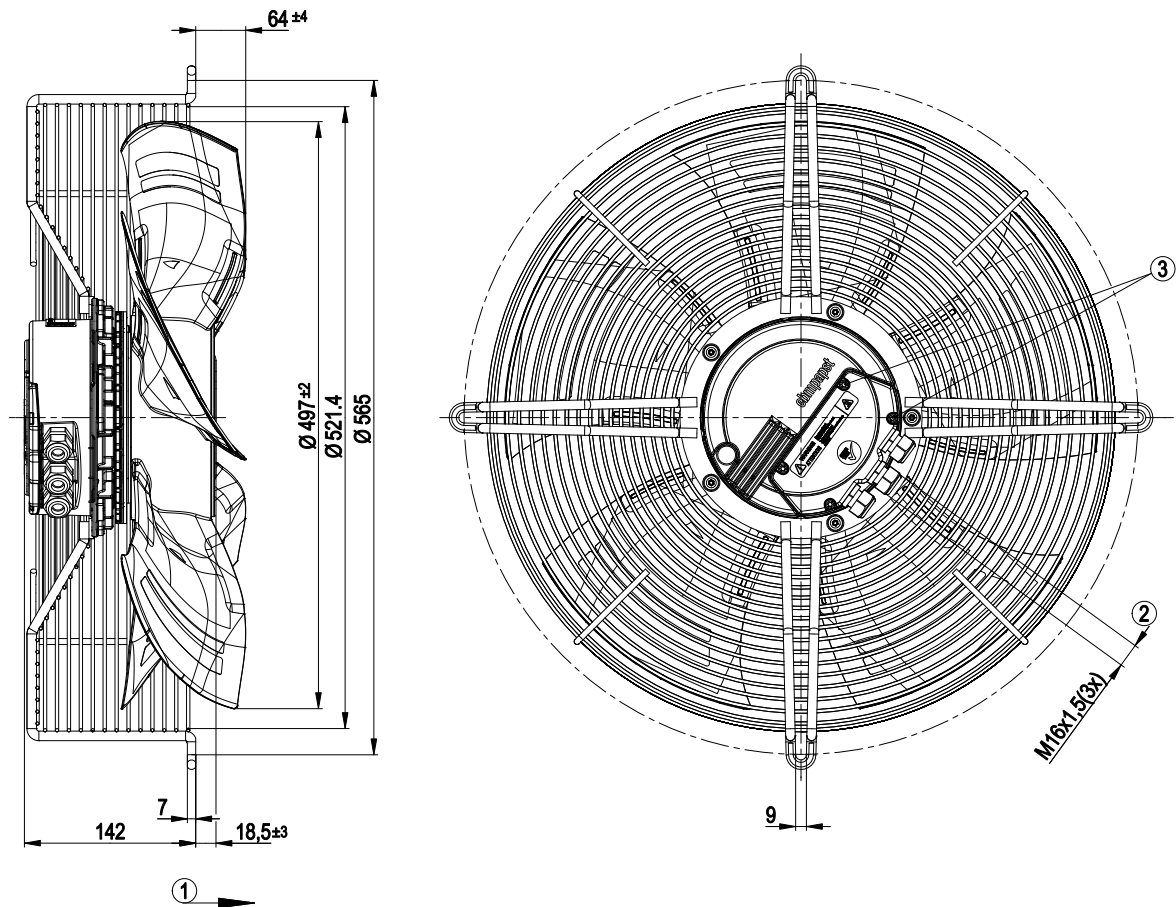


Technical features

Mass	11 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Press-fitted sheet steel blank, sprayed with PP plastic
Material of guard grille	Steel, phosphated and coated in black plastic
Number of blades	5
Direction of air flow	"A"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Alarm relay - PFC, active - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - RS485 ebmBUS - Line undervoltage detection - Motor current limit - Soft start - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Control interface with SELV potential safely disconnected from the mains
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-4 (industrial environment)
Leakage current	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Cable exit	Variable
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1

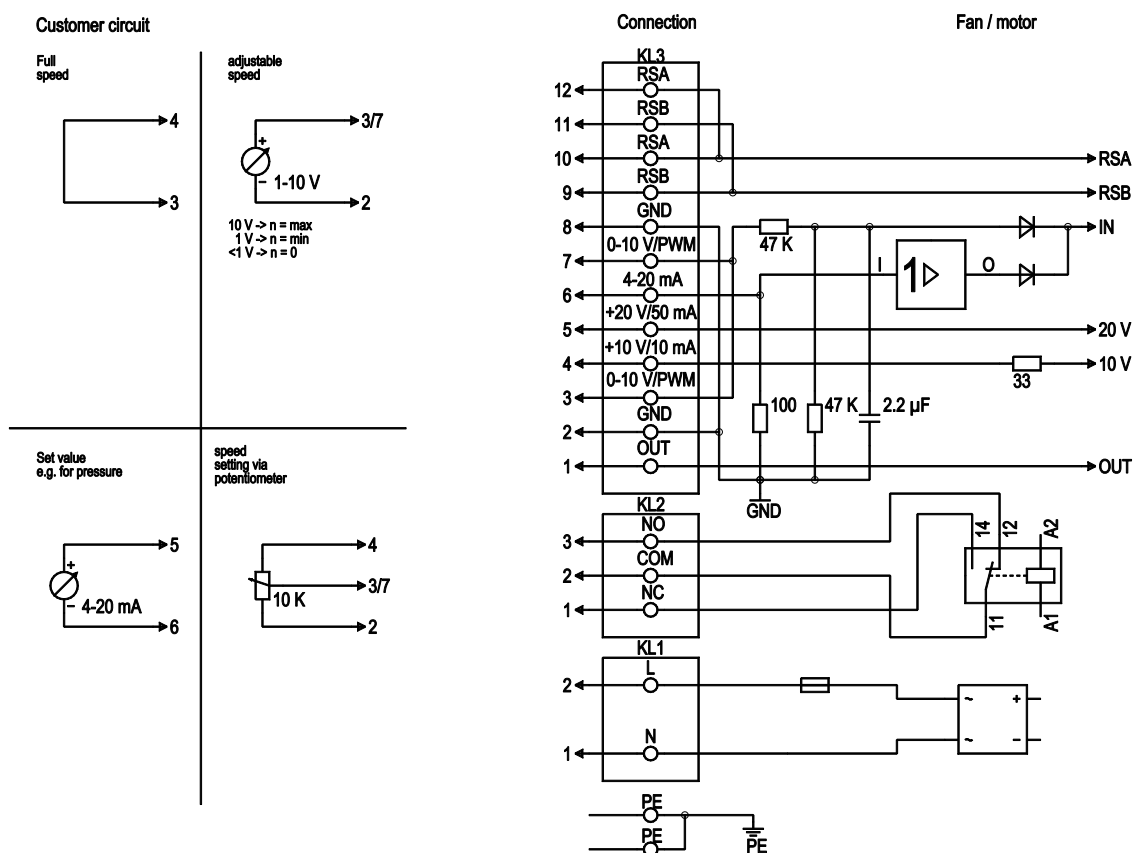


Product drawing



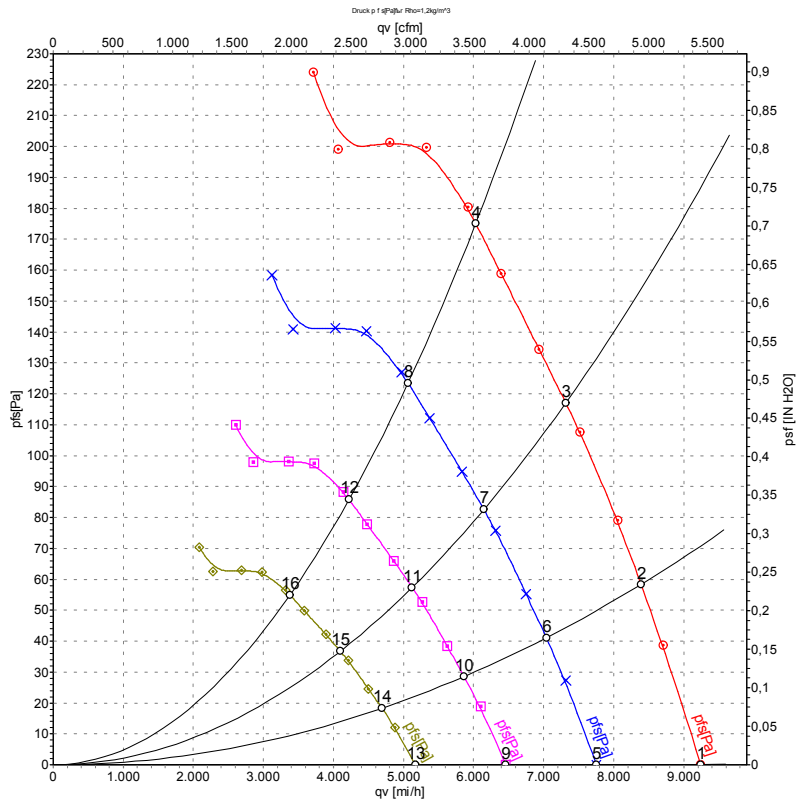
1	Direction of air flow "A"
2	Cable diameter: min. 4 mm; max. 10 mm; tightening torque: 2.5±0.4 Nm
3	Tightening torque 3.5±0.5 Nm

Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2	N, L	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the current motor level control coefficient: 1 V corresponds to 10% level control coefficient, 10 V correspond to 100% level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, supply voltage for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV

Charts: Air flow 50 Hz



Measurement: LU-131222

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: L_{wA} measured as per ISO 13347 /
L_{pA} measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	L _{pA_{in}}	L _{wA_{in}}	L _{wA_{out}}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	230	50	1420	554	2.52	70	77	77	9245	0
2	230	50	1420	633	2.85	67	75	75	8390	58
3	230	50	1420	696	3.12	66	73	73	7315	117
4	230	50	1420	750	3.40	66	74	73	6030	175
5	230	50	1200	327	1.49	66	74	74	7755	0
6	230	50	1200	373	1.68	64	71	71	7040	41
7	230	50	1200	413	1.85	62	69	69	6145	83
8	230	50	1200	443	1.97	62	70	70	5065	124
9	230	50	1000	189	0.86	62	70	70	6460	0
10	230	50	1000	216	0.97	60	67	67	5865	28
11	230	50	1000	239	1.07	58	65	65	5125	57
12	230	50	1000	256	1.14	58	66	66	4220	86
13	230	50	800	97	0.44	58	65	65	5170	0
14	230	50	800	111	0.50	55	62	62	4695	18
15	230	50	800	122	0.55	53	60	60	4100	37
16	230	50	800	131	0.59	54	61	61	3375	55