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**Nominal data**

Type	M3G084-FA15-B5	
Motor	M3G084-FA	
Phase		1~
Nominal voltage	VDC	230
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min <sup>-1</sup>	4000
Power consumption	W	680
Power output	W	570
Current draw	A	3.0
Rated torque	Ncm	135
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	50

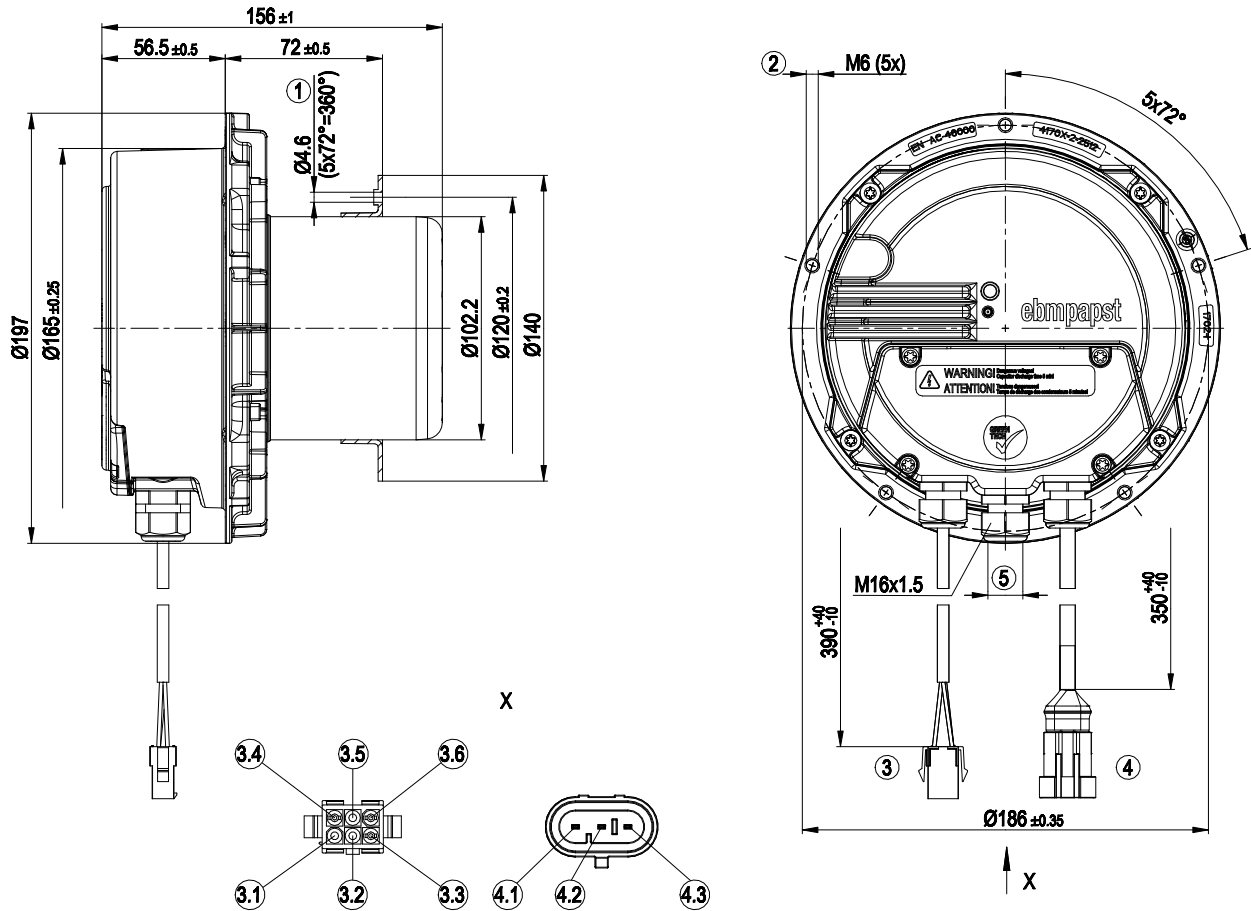
ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change



## Technical description

<b>Weight</b>	4.9 kg
<b>Motor size</b>	84
<b>Rotor surface</b>	Painted black
<b>Electronics housing material</b>	Die-cast aluminum
<b>Direction of rotation</b>	Counterclockwise, viewed toward rotor
<b>Degree of protection</b>	IP54
<b>Insulation class</b>	"B"
<b>Moisture (F) / Environmental (H) protection class</b>	H1
<b>Max. permitted ambient temp. for motor (transport/storage)</b>	+80 °C
<b>Min. permitted ambient temp. for motor (transport/storage)</b>	-40 °C
<b>Installation position</b>	Shaft horizontal or rotor on top
<b>Condensation drainage holes</b>	None
<b>Mode</b>	S1
<b>Motor bearing</b>	Ball bearing
<b>Technical features</b>	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- Alarm relay</li> <li>- Motor current limitation</li> <li>- Emergency operation, standstill on cable break</li> <li>- PFC, active</li> <li>- RS-485 MODBUS-RTU, 38,400 baud, no parity</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from supply</li> <li>- Thermal overload protection for electronics/motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
<b>EMC immunity to interference</b>	According to EN 61000-6-2 (industrial environment)
<b>EMC circuit feedback</b>	According to EN 61000-3-2/3
<b>EMC interference emission</b>	According to EN 61000-6-3 (household environment)
<b>Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)</b>	<= 3.5 mA
<b>Electrical hookup</b>	Connector with cable
<b>Motor protection</b>	Thermal overload protector (TOP) internally connected
<b>With cable</b>	Variable
<b>Protection class</b>	I (with customer connection of protective earth)
<b>Conformity with standards</b>	EN 61800-5-1

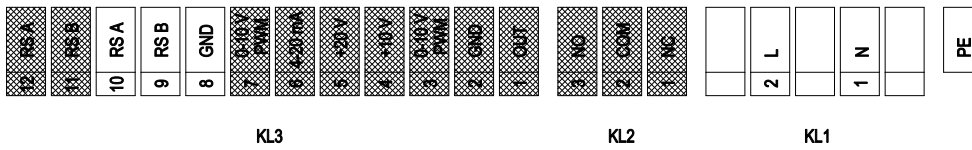
Product drawing



1	Extruded hole according to DIN 7952 for screw with self-tapping thread according to DIN 7500
2	Max. clearance for screw 10 mm
3	Cable PVC AWG22 with crimped connector housing AMP part no. 794940-1 and 3x plug pin AMP part no. 170360-3 with seal 794758-1 and 3x dummy plug 794995-1
3.1	Dummy plug
3.2	Dummy plug
3.3	RSB (red)
3.4	RSA (yellow)
3.5	Dummy plug
3.6	GND (blue)
4	Cable PVC AWG18 with crimped connector housing AMP part no. 282105-1 and 3x flat plug AMP part no. 282109-1 with seal 281934-2
4.1	L (black)
4.2	N (blue)
4.3	PE (green/yellow)
5	Cable diameter min. 4 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm



## Connection diagram



shaded gray =&gt; not brought out via leads

No.	Conn.	Designation	Color	Function/assignment
1	-	PE	green/yellow	Protective earth terminal
1	KL1	N	blue	Power supply, see nameplate for voltage range, 50/60 Hz
1	KL1	L	black	Power supply, see nameplate for voltage range, 50/60 Hz
2	KL2	NC	black	Floating status contact, break for failure
2	KL2	COM	white	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
2	KL2	NO	yellow	Floating status contact, make for failure
-	KL3	OUT		Analog output, 0-10 VDC, max. 3 mA, SELV Output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
2	KL3	GND	blue	Reference ground for control interface, SELV
-	KL3	0-10 V PWM		Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
-	KL3	+10 V		Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
-	KL3	+20 V		Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
-	KL3	4-20 mA		Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
2	KL3	0-10 V PWM	red	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
-	KL3	GND		Reference ground for control interface, SELV
-	KL3	RSB		RS485 interface for MODBUS, RSB
-	KL3	RSA		RS485 interface for MODBUS, RSA
-	KL3	RSB		RS485 interface for MODBUS, RSB
-	KL3	RSA		RS485 interface for MODBUS, RSA

Curves: Speed (rpm)

