

EC centrifugal module - RadiPac

backward curved, single inlet

with support bracket



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Nominal data

Type	K3G500-AP25-01	
Motor	M3G150-FF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	1780
Power input	W	2825
Current draw	A	4.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	66.5	52.3	56.3
Efficiency grade N		72.2	58	62
Power input P_{ed}	kW	2.86		
Air flow q_v	m ³ /h	8140		
Pressure increase p_{fs}	Pa	799		
Speed n	min ⁻¹	1790		

Data definition with optimum efficiency. LU-128476
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



Technical features

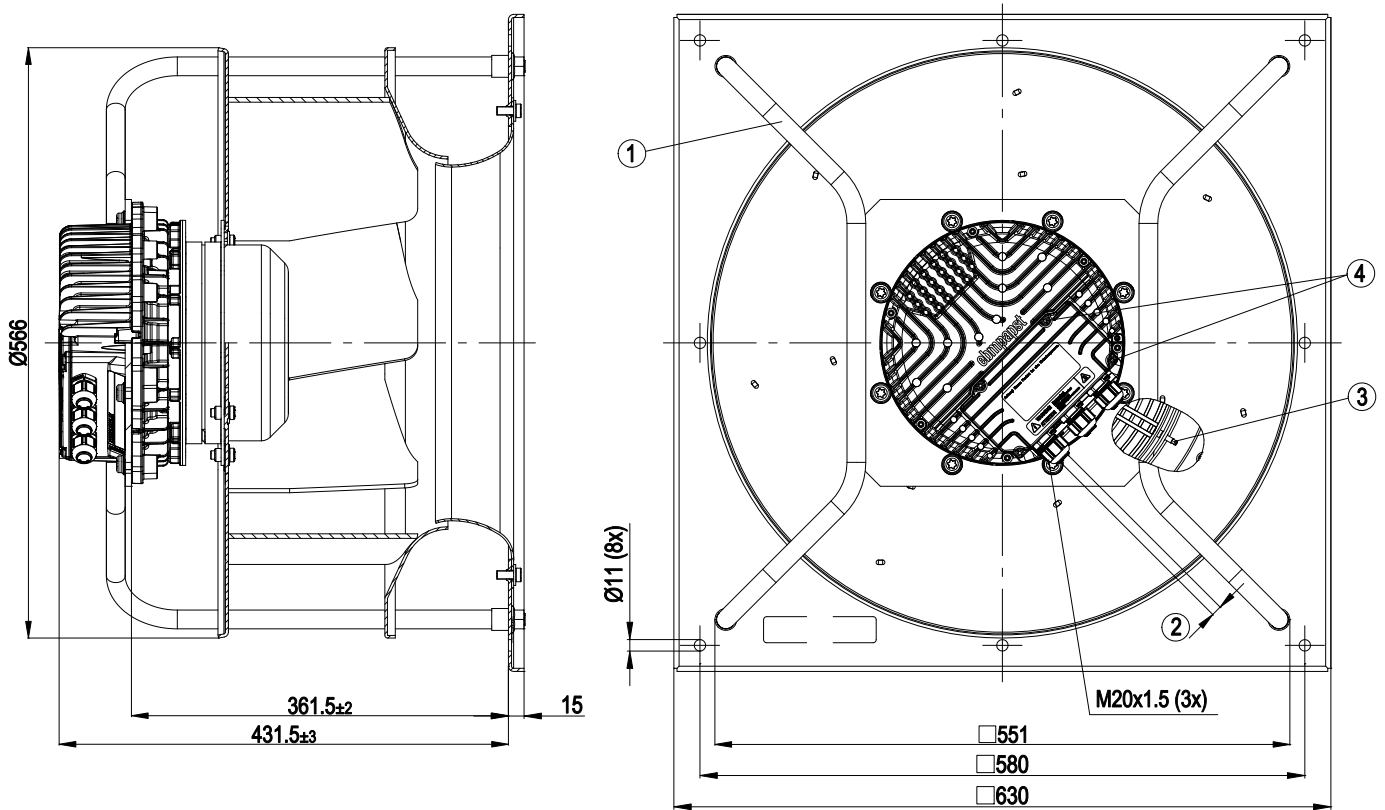
Mass	40 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, hot-dip galvanised
Material of support bracket	Steel, coated in black plastic (RAL 9005)
Material of inlet nozzle	Sheet steel, hot-dip galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- External 24 V input (programming) - RS485 MODBUS-RTU - PFC, passive - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V and 4-20 mA - Output for slave 0-10 V - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730



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Product drawing



1	Installation position: shaft horizontal (install the support struts only vertically as shown in the view!) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm; tightening torque 4 ± 0.6 Nm
3	Inlet nozzle with pressure tap (k-factor: 281)
4	Tightening torque 3.5 ± 0.5 Nm



Connection screen

				8	9	10	11	12	13	14
				Din 2	Din 3	GND	Ain 2 U	+ 20 V	Ain 2 I	Aout
1	RSA									
2	RSB									
3	GND									
4	Ain 1 U									
5	+ 10 V									
6	Ain 1 I									
7	Din 1									
KL 3										
1	NO									
2	COM									
3	NC									
KL 2										
	PE									
PE										
1	L1									
2	L2									
3	L3									
KL 1										

No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV



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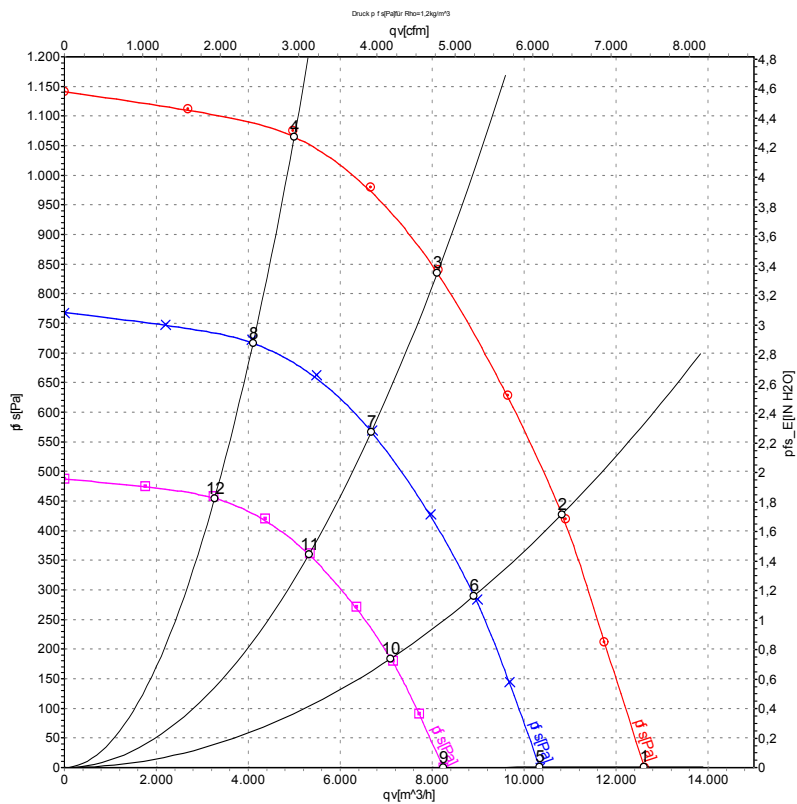
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No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω , parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV



Charts: Air flow 50 Hz



Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: L_{wA} measured as per ISO 13347 /
L_{pA} measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	L _{pA_{in}}	L _{wA_{in}}	L _{wA_{out}}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	400	50	1780	1985	3.09	87	94	99	12610	0
2	400	50	1780	2530	3.90	81	89	93	10820	435
3	400	50	1780	2825	4.30	76	83	88	8110	840
4	400	50	1780	2692	4.14	78	85	90	5000	1075
5	400	50	1475	1094	1.70	83	90	95	10340	0
6	400	50	1475	1411	2.18	77	84	89	8910	294
7	400	50	1475	1602	2.47	72	79	84	6680	572
8	400	50	1475	1484	2.28	74	80	86	4100	722
9	400	50	1175	553	0.86	78	85	90	8240	0
10	400	50	1175	714	1.10	72	80	84	7100	187
11	400	50	1175	810	1.25	67	74	79	5320	363
12	400	50	1175	750	1.15	69	75	81	3265	458

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · L_{pA_{in}} = Sound pressure level inlet side · L_{wA_{in}} = Sound power level inlet side · L_{wA_{out}} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

