

W3G710-DU21-02

EC axial fan - HyBlade®

sickled blades (S series)

with full square nozzle

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General partner: Elektrobau Mulfingen GmbH · Headquarters Mulfingen

County court Stuttgart · HRB 590142



Nominal data

Type	W3G710-DU21-02	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	1250
Power input	W	2830
Current draw	A	4.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+60

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive integrated	Integrated
Specific ratio*	1,00

* Specific ratio = $1 + p_{sf} / 100\,000$

	Actual	Request 2013	Request 2015
Overall efficiency η_e	39,3	32,5	36,5
Efficiency grade N	42,8	36	40
Power input P_e	kW	2,86	
Air flow q_v	m ³ /h	14380	
Pressure increase Total p_{sf}	Pa	267	
Speed n	min ⁻¹	1260	

Data established at point of optimum efficiency

Technical features

Mass	45 kg
Size	710 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Material of wall ring	Sheet steel, pre-galvanised and coated in black plastic
Material of guard grille	Steel, phosphated and coated in black plastic
Number of blades	5
Blade angle	0°
Direction of air flow	"A"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+ 80 °C
Min. permissible ambient motor temp. (transp./storage)	- 40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- RS485 MODBUS RTU - PFC, passive - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - External 24 V input (setting parameters)
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Leakage current	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; UL 1004-7 + 60730

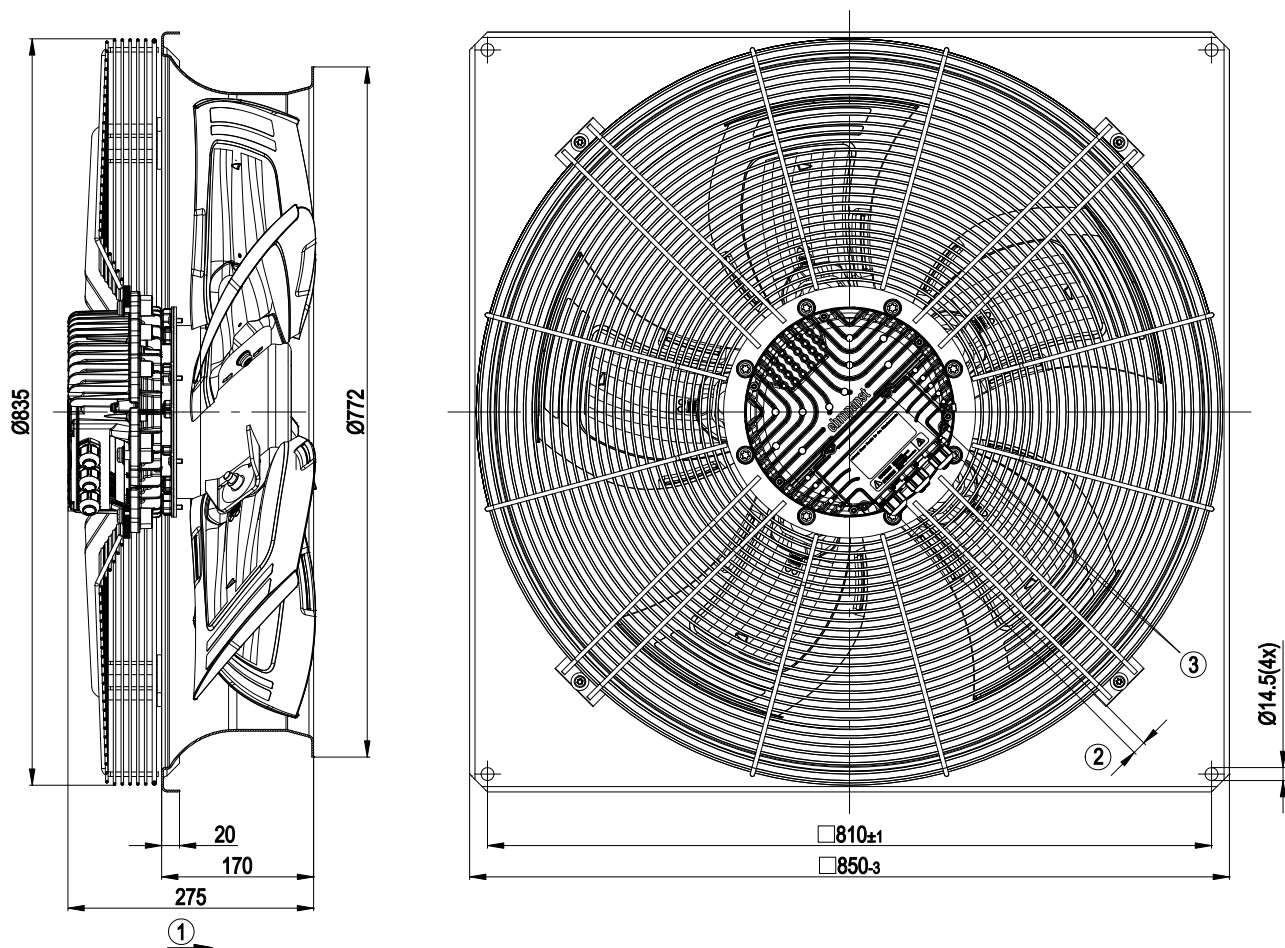
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Product drawing



1	Direction of air flow "A"
2	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm

Connection screen

8	Din 2	RSA	1
9	Din 3	RSB	2
10	GND	GND	3
11	Ain 2 U	Ain 1 U	4
12	+ 20 V	+ 10 V	5
13	Ain 2 I	Ain 1 I	6
14	Aout	Din 1	7

KL 3

NO	1
COM	2
NC	3

KL 2

PE

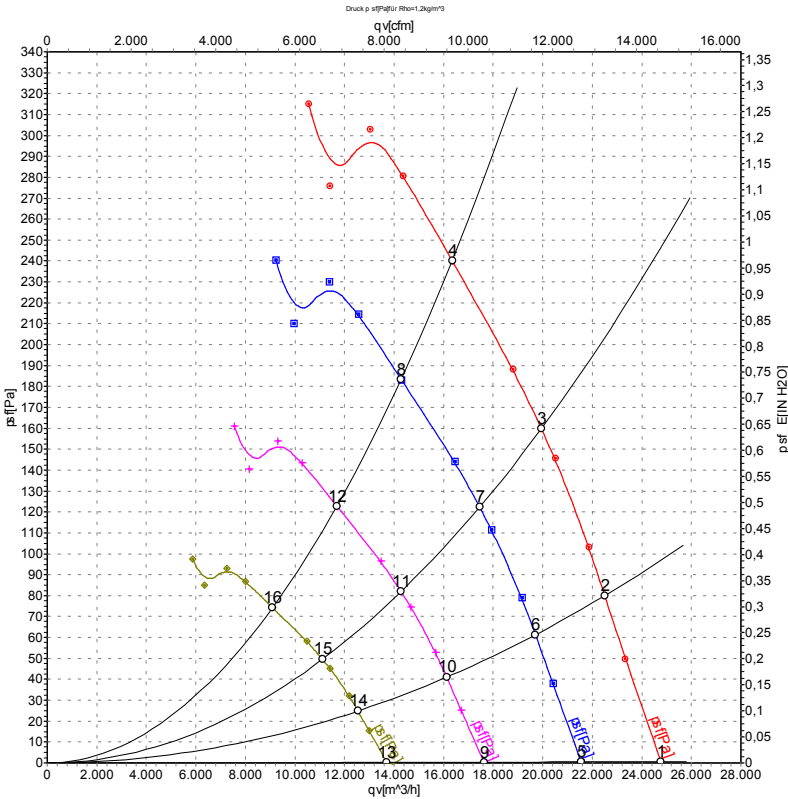
PE

L1	1
L2	2
L3	3

KL 1

No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Signal ground for control interface KL3
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20 V +/-25/-10 %; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed; function selectable per bus; parametrisable curve.

Charts: Air flow 50 Hz



Measurement: LU-120948

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: L_{wA} measured as per ISO 13347 /
L_{pA} measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _e	I	L _{pA_{in}}	L _{wA_{in}}	L _{wA_{out}}	qv	P _{sf}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m³/h	Pa
1	400	50	1250	2227	3.40	71	79	81	24770	0
2	400	50	1250	2420	3.70	71	79	80	22500	80
3	400	50	1250	2649	4.02	72	79	80	19940	160
4	400	50	1250	2830	4.30	75	83	82	16350	240
5	400	50	1100	1465	2.24	68	76	78	21540	0
6	400	50	1100	1624	2.48	68	76	77	19700	61
7	400	50	1100	1775	2.69	69	76	77	17450	122
8	400	50	1100	1884	2.87	73	80	79	14290	183
9	400	50	900	802	1.23	64	72	73	17630	0
10	400	50	900	890	1.36	64	72	72	16120	41
11	400	50	900	972	1.48	65	72	73	14280	82
12	400	50	900	1032	1.57	68	75	74	11690	123
13	400	50	700	378	0.58	59	66	68	13710	0
14	400	50	700	418	0.64	59	66	67	12540	25
15	400	50	700	457	0.69	59	67	67	11110	50
16	400	50	700	486	0.74	63	70	69	9090	74

