

A3G710-AU21-35

EC axial fan - HyBlade®

sickled blades (S series)

for agricultural ventilation



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Nominal data

Type	A3G710-AU21-35	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min ⁻¹	1250
Power input	W	2830
Current draw	A	4.3
Max. back pressure	Pa	240
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = $1 + p_b / 100\,000\text{ Pa}$

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	39.3	32.5	36.5
Efficiency grade N		42.8	36	40
Power input P_{ed}	kW	2.86		
Air flow q_v	m ³ /h	14380		
Pressure increase p_{fs}	Pa	267		
Speed n	min ⁻¹	1260		

Data definition with optimum efficiency.

LU-120948

The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.



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Technical features

Mass	25.6 kg
Size	710 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert (coated in black), sprayed with PP plastic
Number of blades	5
Blade angle	0°
Direction of air flow	"A"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F5
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on top; rotor on bottom on request
Condensate discharge holes	On the stator side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

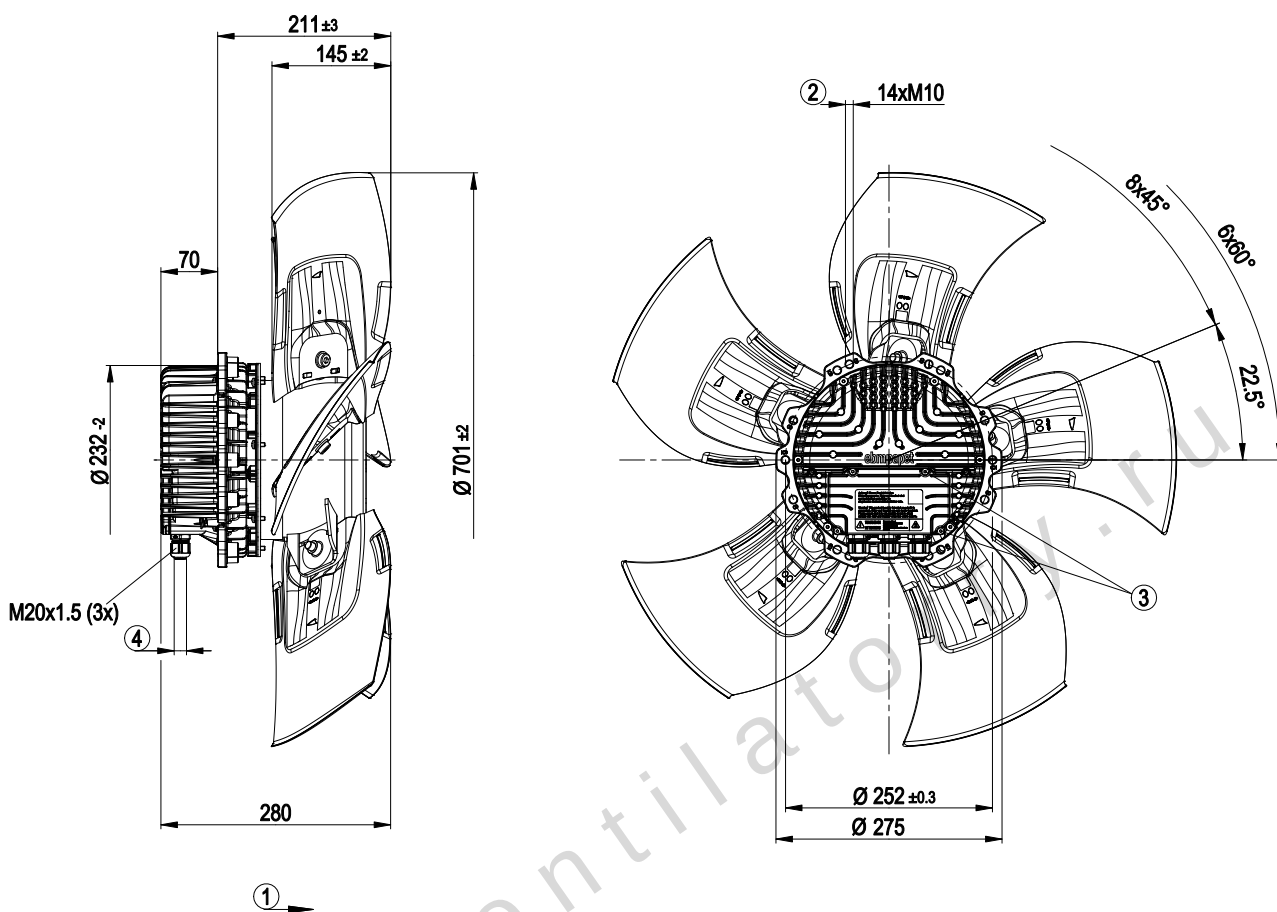
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Product drawing



1	Direction of air flow "A"
2	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm
3	Depth of screw max. 25 mm
4	Tightening torque 3.5±0.5 Nm

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Connection screen

1	RSA	Din 2	8
2	RSB	Din 3	9
3	GND	GND	10
4	Ain 1 U	Ain 2 U	11
5	+ 10 V	+ 20 V	12
6	Ain 1 I	Ain 2 I	13
7	Din 1	Aout	14

KL 3

1	NO
2	COM
3	NC

KL 2

PE

PE

1	L1
2	L2
3	L3

KL 1

No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, $R_i = 100 \text{ k}\Omega$, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V $\pm 3\%$, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; $R_i = 100 \text{ }\Omega$, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, $R_i = 100 \text{ k}\Omega$, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V $\pm 25/-10\%$, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV

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No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω , parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

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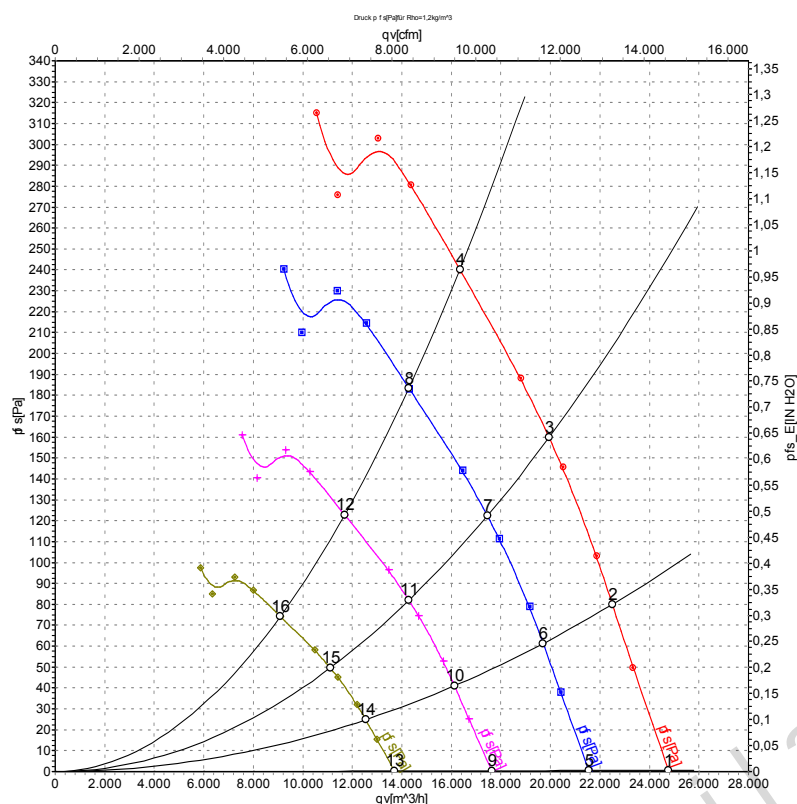
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Charts: Air flow 50 Hz



Measurement: LU-120948

Air performance measured as per ISO 5801
Installation category A. For detailed
information on the measuring set-up, please
contact ebm-papst. Suction-side noise
levels: LwA measured as per ISO 13347 /
LpA measured with 1m distance to fan axis.
The values given are valid under the
measuring conditions mentioned above and
may vary according to the actual installation
situation. With any deviation from the
standard set-up, the specific values have to
be checked and reviewed with the unit
installed.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	qv	p _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa
1	400	50	1250	2227	3.40	71	79	81	24770	0
2	400	50	1250	2420	3.70	71	79	80	22500	80
3	400	50	1250	2649	4.02	72	79	80	19940	160
4	400	50	1250	2830	4.30	75	83	82	16350	240
5	400	50	1100	1465	2.24	68	76	78	21540	0
6	400	50	1100	1624	2.48	68	76	77	19700	61
7	400	50	1100	1775	2.69	69	76	77	17450	122
8	400	50	1100	1884	2.87	73	80	79	14290	183
9	400	50	900	802	1.23	64	72	73	17630	0
10	400	50	900	890	1.36	64	72	72	16120	41
11	400	50	900	972	1.48	65	72	73	14280	82
12	400	50	900	1032	1.57	68	75	74	11690	123
13	400	50	700	378	0.58	59	66	68	13710	0
14	400	50	700	418	0.64	59	66	67	12540	25
15	400	50	700	457	0.69	59	67	67	11110	50
16	400	50	700	486	0.74	63	70	69	9090	74

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side

qv = Air flow · p_{fs} = Pressure increase